A Simple Model with Myofilament Compliance Predicts Activation-Dependent Crossbridge Kinetics in Skinned Skeletal Fibers

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ABSTRACT The contribution of thick and thin filaments to skeletal muscle fiber compliance has been shown to be significant. If similar to the compliance of cycling cross-bridges, myofilament compliance could explain the difference in time course of stiffness and force during the rise of tension in a tetanus as well as the difference in Ca^{2+} sensitivity of force and stiffness and more rapid phase 2 tension recovery (r) at low Ca^{2+} activation. To characterize the contribution of myofilament compliance to sarcomere compliance and isometric force kinetics, the Ca^{2+}-activation dependence of sarcomere compliance in single glycerinated rabbit psoas fibers, in the presence of ATP (5.0 mM), was measured using rapid length steps. At steady sarcomere length, the dependence of sarcomere compliance on the level of Ca^{2+}-activated force was similar in form to that observed for fibers in rigor where force was varied by changing length. Additionally, the ratio of stiffness/force was elevated at lower force (low $[Ca^{2+}]$) and r was faster, compared with maximum activation. A simple series mechanical model of myofilament and cross-bridge compliance in which only strong cross-bridge binding was activation dependent was used to describe the data. The model fit the data and predicted that the observed activation dependence of r can be explained if myofilament compliance contributes 60–70% of the total fiber compliance, with no requirement that actomyosin kinetics be $[Ca^{2+}]$ dependent or that cooperative interactions contribute to strong cross-bridge binding.

INTRODUCTION

Upon activation, skeletal muscle develops force that is accompanied by an increase in fiber and sarcomere stiffness (K_S) and a corresponding decrease in compliance ($C_S = 1/K_S$). The decrease in C_S upon activation has been attributed to increased interaction of myosin cross-bridges with actin (Ford et al., 1981). This interpretation was justified by the observations that 80–90% of fiber compliance could be attributed to cross-bridges, with the remaining fraction being attributed to other structural elements in series with the cross-bridges, such as z-bands, thick and thin filaments, and cytoskeletal elements (Ford et al., 1981; Bagni et al., 1988; Tawada and Kimura, 1984). Subsequently, measurements of K_S and C_S have been used to describe the strength of binding and distribution of actomyosin cross-bridges between mechanochemical states. For example, the dissociation of force and stiffness during the rise of force in a tetanus (Ford et al., 1986; Bagni et al., 1988), at steady submaximal force (Martyn and Chase, 1995) and force inhibition with phosphate (Pi) (Martyn and Gordon, 1992; Regnier et al., 1995; Dantzig et al., 1992), have been interpreted to indicate the presence of attached non-force-generating states in the cross-bridge cycle. However, evidence that a significant fraction (50–70%) of fiber compliance is attributable to the elastic properties of the thick and thin filaments (Higuchi et al., 1995; Huxley et al., 1994; Linari et al., 1998; Wakabayashi et al., 1994; Kojima et al., 1994) raises new questions about interpretation of muscle mechanical data.

The presence of a substantial non-cross-bridge compliance would result in a partition of an applied length change between cross-bridges and the compliant structures in series with them (Higuchi et al., 1995). For example, when force is low because there are relatively few strongly bound cross-bridges (e.g., low Ca^{2+} activation or in the presence of inhibitors) the change in length of the most compliant structure, in this case cross-bridges, would be disproportionately larger than for less compliant structures. Likewise, as the degree of cross-bridge interaction and force increases, the relative compliance of that component decreases and a greater fraction of any length change is applied to the myofilament component of fiber compliance. As a consequence, when a rapid step decrease in sarcomere length (SL) is applied to the fiber, the amplitude necessary to cause force development by cross-bridges to drop to zero (Y_0) (Huxley and Simmons, 1971, 1972) would be smaller at lower levels of force. A decrease in Y_0 and the corresponding increase in the stiffness/force ratio could be explained by the presence of a large compliance in series with cross-bridges and not necessarily by redistribution between cross-bridge states (Martyn and Chase, 1995; Martyn and Gordon, 1992). Luo et al. (1994) have further suggested that myofilament compliance in series with an activation-dependent cross-bridge compliance could result in slower tension transients. Thus, at lower forces myofilament compliance would be less than cross-bridge compliance and tension transients would be faster than at higher forces, where more of the total fiber compliance would be attributable to cross-bridges. This could explain the inverse relation between force and the rate of phase 2 tension recovery (r) when

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steady force is altered either by Ca^{2+} (Martyn and Chase, 1995) or Pi (Martyn and Gordon, 1992), as well as during the rise of tetanic tension in intact fibers (Ford et al., 1986; Bagni et al., 1988; Linari et al., 1998).

To test whether a significant non-cross-bridge compliance can explain the activation dependence of C_S, Y_0, and r we measured the dependence of fiber stiffness and r on the level of isometric force when force was varied by changing $[Ca^{2+}]$, was inhibited with AlF^{4-} at maximal activating $[Ca^{2+}]$ (Chase et al., 1994), or was activated in the absence of Ca^{2+} with a modified form of cardiac troponin C (aTnC) (Hannon et al., 1993). To minimize any change in compliance that might result from changes in myofilament overlap (Higuchi et al., 1995), particular care was taken to maintain steady SL constant throughout contractures. At steady SL, C_S and Y_0 decreased at low forces and phase 2 tension transients (r) were faster compared with maximum activation.

The data were fit with a simple model in which sarcomere stiffness is distributed between thick and thin filaments and all other sarcomeric structures (K_{myo}), in series with the stiffness of the population of interacting cross-bridges (K_X), which depends on the level of thin filament activation. This model is similar to that used by Luo et al. (1994) and Higuchi et al. (1995) to describe their results, with the addition of a viscous element (coefficient of viscosity = η_X), which simplistically simulates a kinetic component. The model accurately described the force dependence of isometric phase 2 kinetics (r) whether force was modulated by varying $[Ca^{2+}]$, by inhibition with alumino-fluoride (AlF^{4-}) in the presence of saturating $[Ca^{2+}]$ or when fibers were activated in the absence of Ca^{2+} and predicted that the myofilament compliance was 60–76% of C_S.

MATERIALS AND METHODS

Rabbits were housed in the Department of Comparative Medicine at the University of Washington and cared for in accordance with the U.S.A. National Institutes of Health Policy on Humane Care and Use of Laboratory Animals. All protocols were approved by the University of Washington Animal Care Committee.

Fiber preparation

Segments of single muscle fibers from glycerinated rabbit psoas were prepared as described elsewhere (Chase and Kushmerick, 1988). Rabbits were first sedated with ketamine (40 mg kg^{-1}) and xylazine (5 mg kg^{-1}) and then anesthetized by continuous perfusion with ketamine (19.4 mg ml^{-1}) and xylazine (0.83 mg ml^{-1}) in saline through the marginal ear vein. Fiber end compliance was minimized by regional micro-application of 1% glutaraldehyde (Chase and Kushmerick, 1988). Isolated fiber segments were treated with 1% Triton X-100 in pCa 9.2 solution for 10 min to ensure perforation of membranous elements. Fiber segments were attached via aluminum foil T-clips to small wire hooks on the mechanical apparatus. After each experiment, we determined the total length of the two chemically fixed regions at the ends of the fiber segment, as described (Chase and Kushmerick, 1988); the total fixed length was subtracted from the overall length to obtain the unfixed fiber length (L_F). Variations in C_S and the kinetics of phase 2 tension recovery with pCa, and thus isometric force level, could not be attributed to activation-dependent alterations in myofilament lattice spacing that occur in skinned fiber preparations (Brenner, 1983), because these force-dependent changes in lattice spacing were minimized by the presence of 4% w/v Dextran T-500 in all solutions (see Solutions) (Matsubara et al., 1985). At SL = 2.45 ± 0.01 μm (mean ± SEM; n = 7 fibers) fiber diameter was 53.5 ± 4.0 μm at pCa 9.2 and was unchanged at pCa 4.0.

Mechanical apparatus

Force was measured with an AE 801 (Aksjeselkapet Mikro-elektronikk, Horten, Norway) force transducer (peak-to-peak noise equivalent to 0.3 mg; resonant frequency, 7 kHz). A Cambridge Technology (Watertown, MA) model 300 servo motor (−3-dB amplitude response at 2.4 kHz) was used to control fiber length (L_F). SL was continuously monitored by helium-neon laser diffraction as previously described (Chase et al., 1993). Steady-state SL and fiber diameter was determined at ×400 magnification.

Data acquisition and control

Data were acquired during continuous, steady-state submaximal and maximal (pCa 4.0) Ca^{2+} activation. Fiber mechanical properties and structure were maintained during prolonged activation by applying transient release/restretch changes in L_F (Brenner, 1983). Measurements of isometric force, sarcomere stiffness (K_S), and force transient kinetics were made during the steady-state period between the Brenner cycles of unloading/restretch. The force baseline for each condition was determined during a large-amplitude, slack release. Fiber force was normalized to cross-sectional area, calculated from the diameter assuming circular geometry.

Both sarcomere stiffness (K_S) and kinetics of the early phase of force recovery were determined from force and SL responses to rapid, step changes in L_F (Ford et al., 1977; Huxley and Simmons, 1972; Martyn and Chase, 1995). Step changes in L_F were implemented as 350-ms ramp changes in length. Signals were recorded by digitizing 2048 points with 12-bit resolution at a rate of 20 kHz per channel. To prevent aliasing, all signals were passed through a computer-controlled signal processor (CyberAmp 380; Axon Instruments, Foster City, CA) and filtered at 40% of the sampling frequency. K_S was determined from the slope of the relation between the maximum change in force (T_1) following the L_F step and the corresponding change in SL ($-4 < \Delta SL < 8$ nm (h s)$^{-1}$) (Chase et al., 1993; Martyn and Chase, 1995). The ΔSL intercept of this relationship (Y_0; nm (h s)$^{-1}$) was obtained by extrapolation of this regression to the ordinate. T_1 was normalized to cross-sectional area (mN mm^{-2}) and ΔSL was normalized to the initial SL. K_S (MPa = 10^6 N m^{-2}), was determined and sarcomere compliance (C_S) expressed as $K_S^{-1} \times (SL_i/2) \times 1000$ ((nm (h s)$^{-1}$) × (kN M^{-2})$^{-1}$), where SL_i is the initial SL (μm).

The unprocessed, digitized data were analyzed using custom software. Reduced data were further analyzed by linear least-squares regression (Excel version 4.0 for Windows, Microsoft Corp., Redmond, WA) or by nonlinear least-squares regression (SigmaPlot version 4.1, Jandel Scientific, San Rafael, CA). Statistical analyses were performed using Excel (version 4.0 for Windows, Microsoft Corp., Redmond, WA). Student's t-test was used to compare data, with differences considered significant at the 95% confidence level ($p < 0.05$).

Solutions

Relaxing and activating solutions were prepared as described previously (Martyn and Chase, 1995) and contained 5 mM Mg^{2+}-ATP, 15

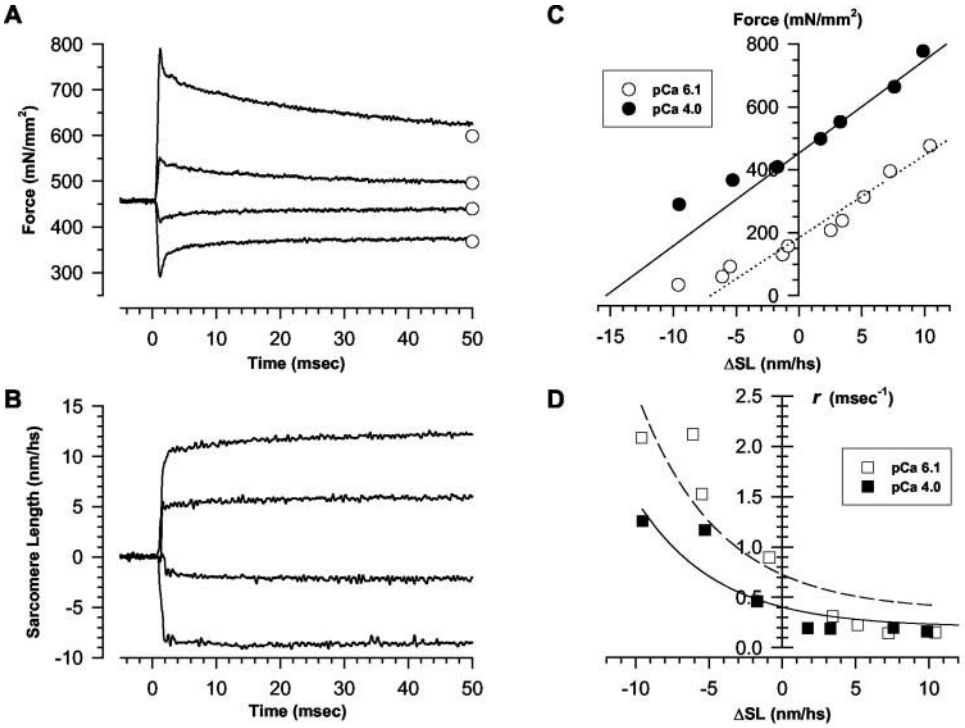

FIGURE 1 Transient changes in force (*A*) and SL (*B*) resulting from steps in fiber length applied to a single activated rabbit psoas fiber. SL remained relatively steady following each length step. The peak change in force (T_1) was followed by a rapid partial recovery (phase 2) toward a steady force (T_2), before the final recovery to the isometric level of force (not shown). T_2 is indicated by the open circles to the right of the corresponding force traces in *A*. To determine C_S ($1/K_S$) at each steady SL force level, changes in T_1 were plotted against the corresponding changes in SL, and K_S was determined from the slope of the relationship, as illustrated in *C*. K_S was determined at maximal (pCa 4.0; ●) and submaximal activating [Ca^{2+}] (pCa 6.1; ○). For each condition Y_0, the amplitude of SL decrease necessary to decrease T_1 to zero was determined by linear extrapolation of the T_1-ΔSL relationship between ± 4.0 nm (h s)$^{-1}$ (*C*). In *D*, the dependence of phase 2 tension recovery rate (*r*) on the amplitude of the step in SL at pCa 4.0 (■) and 6.1 (□) is illustrated.

mM phosphocreatine (PCr), 15 mM EGTA, at least 40 mM MOPS, 135 mM $Na^+ + K^+$, 1 mM Mg^{2+}, pH 7.0, 250 U/ml creatine phosphokinase (CK), and Dextran T-500 (4% w/v; Pharmacia, Piscataway, NJ). To alter solution [Ca^{2+}], varying amounts of calcium propionate were added as determined with a computer program taking into account the desired free [Ca^{2+}] and the binding constants of all solution constituents for Ca^{2+}; ionic strength was maintained constant (200 mM) by varying [MOPS] appropriately at each pCa. The experimental temperature was 10–11°C and varied by <1°C during an experiment.

RESULTS

[Ca^{2+}] dependence of fiber compliance and Y_0

When force and SL reached steady levels during Ca^{2+} activation, stiffness was measured by applying rapid length steps to the fibers (Huxley and Simmons, 1972; Ford et al., 1977), as illustrated in Fig. 1. Maximum Ca^{2+}-activated (pCa 4.0) control force was 390 ± 33.0 mN mm^{-2} at SL = 2.45 ± 0.01 μm (mean ± SD; n = 7 fibers). For the same fibers, relaxed force (pCa. 9.2) was 1.7 ± 0.5% of the maximum.

Transient changes in force (Fig. 1 *A*) and SL (Fig. 1 *B*) resulting from steps in L_F from a single Ca^{2+}-activated rabbit psoas fiber are shown. During transient measurements, SL remained steady at each L_F. Following each step, the peak change in force (T_1) was followed by a rapid partial recovery (phase 2) toward a steady force (T_2), before the final recovery to the isometric level of force (not shown). T_2 is indicated by the open circles to the right of the corresponding force traces in the top panels of Fig. 1 *A*. To determine C_S ($1/K_S$) at each steady SL and force level, changes in T_1 were plotted against the corresponding changes in SL, and the slope of the relationship (K_S) was determined, as illustrated in Fig. 1 *C*. For each condition Y_0, the amplitude of SL decrease that was large enough to cause T_1 to drop to zero was determined by linear extrapolation of the $T_1 - \Delta SL$ relationship between −4.0 and +6.0 nm (h s)$^{-1}$. In Fig. 1 *D* the dependence of phase 2 tension recovery rate (*r*) on the amplitude of the step in SL is illustrated for the experiment shown in Fig. 1 *C*. Because phase 2 tension recovery is not accurately described by a single exponential (Davis and Rodgers, 1995), the rate of tension recovery from T_1 to T_2 was characterized by the time required for tension to change from T_1 by 50% of the difference between T_1 and T_2 ($r = t_{0.5}^{-1}$).

At each [Ca^{2+}] the ΔSL dependence of r (for stretches and releases) was modeled as described by Huxley and Simmons (1971). In this model, during force generation cross-bridges are in equilibrium between two attached states. The distribution between these states is determined by a forward rate constant (k^+) that is dependent on cross-bridge strain and a reverse rate constant (k^-) that is strain independent. The relation between k^+ and k^- was defined as $k^+ = k^-(e^{-yKh/kT})$, where y is the cross-bridge extension, K is the cross-bridge stiffness, h is the cross-bridge motion associated with the transition, k is the Boltzman constant, and T is the temperature. The rate of transition to a new equilibrium distribution is $r = k^+ + k^-$, or:

$$t_{0.5}^{-1} \approx r = k^-(1 + e^{-yKh/kT}) = k^-(1 + e^{-y\alpha}), \qquad (1)$$

where $\alpha = Kh/kT$. Data from each fiber were fit using nonlinear regression analysis to Eq. 1 (Huxley and Simmons, 1971) (Fig. 1 *D*), yielding the value of k^- and α. As found for both intact frog skeletal fibers (Ford et al., 1977) and skinned rabbit psoas fibers (Martyn and Chase, 1995), Eq. 1 did not completely describe the r-ΔSL relation, tending to over estimate r for larger stretches.

The relationship between C_S and force at varying [Ca^{2+}] obtained at an SL of 2.47 ± 0.01 μm (mean ± SEM; $n = 7$ fibers) is summarized in Fig. 2 *A*. The results are similar in appearance to those obtained by Higuchi et al. (1995) where cross-bridge strain was altered in fibers in the rigor state. At maximal force levels our values of C_S are ~55% of that observed for skinned rabbit psoas fibers in rigor (Higuchi et al., 1995). The [Ca^{2+}] dependence of Y_0 corresponding to the values of C_S in Fig. 2 *A* is described in Fig. 2 *B*. Y_0 increased as the level of force increased, as we have previously shown (Martyn and Gordon, 1992; Martyn and Chase, 1995). At maximal levels of Ca^{2+}-activated force the value of Y_0 was −9.8 ± 0.5 μm (mean ± SEM; $n = 7$ fibers). Interestingly, at low levels of isometric force the value of Y_0 extrapolated to ~4 nm per half-sarcomere, a value that is similar to that measured for the power stroke of single isolated myosin motors (Malloy et al., 1995). The results in Fig. 2 *B* can be described by the regression $Y_0 = Y_{min} + Y_{max}(f(K_X^*)/K_{myo})$, where Y_{min} and Y_{max} are the values of Y_0 extrapolated to minimal and maximum levels of activation and f is the normalized value of isometric force. Thus, the activation dependence of Y_0 could be explained if at pCa 4.0 ($f = 1.0$) the ratio of K_X/K_{myo} was 0.40 (4.0 nm/10.0 nm), so that of the applied 10 nm (h $s)^{-1}$ step, only 40% was taken up by cross-bridges with the remainder being applied to the myofilaments. This analysis assumes that K_{myo} is not activation dependent. The results in Fig. 2 *B* are similar to recent data from frog intact skeletal muscle fibers in which the isometric force dependence of stiffness and Y_0 was measured (Linari et al., 2002). However, the value of Y_0 at pCa 4.0 obtained from psoas skinned fibers at 10°C (Table 1) is larger than reported for frog intact fibers at lower temperatures (4–5 nm (h $s)^{-1}$) (Piazzesi et al., 1992). This difference is probably less because decreasing temperature causes a decrease in maximal Ca^{2+}-activated force in rabbit skinned psoas fibers (Ranatunga, 1996). Thus, skinned psoas fibers at 0–5°C would generate ~50% less force and, referring to Fig. 2 *B* at 50% relative force, Y_0 would decrease to ~7.5 nm (h $s)^{-1}$.

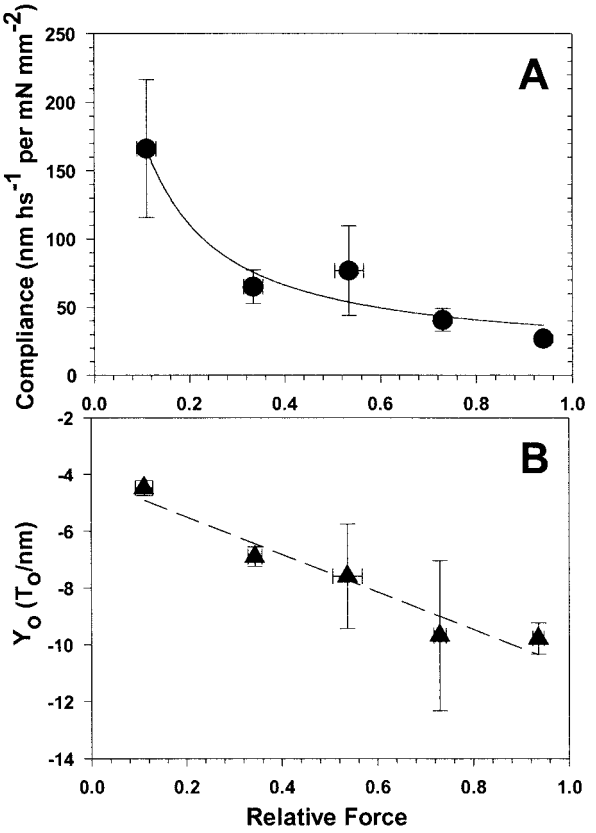

FIGURE 2 (*A*) The relationship between sarcomere compliance (C_S) and relative force obtained at 2.47 ± 0.01 μm SL (●; mean ± SEM; $n = 7$ fibers). Data were binned in intervals of 20% relative force. Submaximal forces are normalized to force at pCa 4.0. (*B*) Dependence of Y_0 (▲) on Ca^{2+}-activated force for the data in *A*. The results in *B* were fit by line regression to the equation $Y_0 = Y_{min} + Y_{max} \times (f(K_X^*)/K_{myo})$ (– – –), where Y_{min} and Y_{max} are the values of Y_0 extrapolated to minimal and maximum levels of activation. Regression parameter estimates are given in Results.

[Ca^{2+}] dependence of phase 2 kinetics

The dependence of r on ΔSL was determined at different activating [Ca^{2+}] (pCa 6.4–4.0) and fit with Eq. 1, yielding values of k^- and α. In Fig. 3 the r-ΔSL relation is compared for data pooled from six fibers when force was 34.0 ± 2.0% (▲) and 94.0 + 2.0% (●) of maximum (pCa 4.0). The value of r at its y-axis intercept is twice the value of k^- (Huxley and Simmons, 1971, 1972). The data in Fig. 3 indicate that

TABLE 1 The dependence of the rate of tension recovery during phase 2 of the transient force response to a quick step in SL on the size of the length step was fit with Eq. 2

Condition	*n*	Relative force	k^-	*Kh*/*kt*	Y_0
Ca	7	0.14 ± 0.01	0.57 ± 0.05	0.16 ± 0.01	−4.47 ± 0.27
Ca	6	0.34 ± 0.01	0.37 ± 0.06	0.19 ± 0.01	−6.90 ± 0.34
Ca	6	0.50 ± 0.03	0.32 ± 0.05	0.22 ± 0.02	−7.58 ± 1.80
Ca	5	0.73 ± 0.01	0.27 ± 0.04	0.25 ± 0.06	−9.70 ± 2.60
Ca	7	0.93 ± 0.02	0.27 ± 0.04	0.19 ± 0.02	−9.80 ± 0.55
Ca (AlF^4 control)	5	0.99 ± 0.01	0.42 ± 0.08	0.20 ± 0.03	−12.9 ± 2.80
Ca (post-recovery)	4	0.78 ± 0.02	0.39 ± 0.06	0.28 ± 0.03	−10.5 ± 0.59
Ca (during recovery)	3	0.22 ± 0.07	0.75 ± 0.11	0.18 ± 0.02	−6.8 ± 0.56
200 μm AlF^{4-}	2	0.16 ± 0.20	0.65 ± 0.10	0.14 ± 0.04	−3.8
500 μm AlF^{4-}	5	0.03 ± 0.01	0.91 ± 0.09	0.16 ± 0.03	−3.2 ± 0.24
aTnC (4.0 control)	2	1	0.30 ± 0.08	0.27 ± 0.05	
Part aTnC (9.2)	2	0.26 ± 0.01	0.55 ± 0.01	0.30 ± 0.03	
Full aTnC (9.2)	2	0.67 ± 0.01	0.25 ± 0.04	0.34 ± 0.03	

Data were obtained from experiments in which steady isometric force was altered by changing $[Ca^{2+}]$, by inhibiting force with alumino-fluoride (AlF^{4-}), or by selective reconstitution of skinned fibers with a constitutatively activating cardiac TnC (aTnC) in the absence of Ca^{2+}.

tension recovery during tension transient phase 2 is faster at lower levels of force, as previously described (Martyn and Chase, 1995; Bagni et al., 1988, 1999).

The model

To test whether the Ca^{2+}-activation dependence of *r*, described in Figs. 1–3, results primarily from the presence of a significant myofilament compliance and not from an activation dependence of cross-bridge kinetics, we propose a model that predicts the fraction of total C_S due to myofilaments necessary to describe the data. The model consists of two elastic components K_{myo} and K_X in series with a kinetic element, represented by a dash pot with viscocity η_X (Fig. 4 *A*). K_{myo} represents all components of elasticity with the sarcomere other than that of the population of cross-bridges in the overlap zone between thick and thin filaments, whereas K_X represents the cross-bridge component of elasticity that can vary with the level of strong actomyosin interaction (Fig. 4 *A*). We have made no attempt to model the distribution of myofilament strain along the overlap zone (Daniel et al., 1998; Mijailovich et al., 1996)

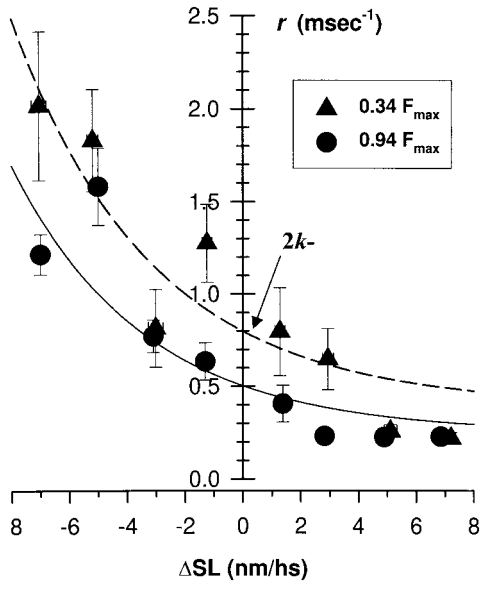

FIGURE 3 Dependence of the rate of tension recovery following step changes in fiber length (*r*) upon the corresponding SL changes. Data were pooled from six fibers at 94% ± 2.0% (●) and 34% ± 2.05 (▲) maximum Ca^{2+}-activated force (mean ± SEM; $n = 6$ fibers). At each force level, the *r*- ΔSL relation was fit by Eq. 1 (*dashed* and *solid lines*). The intercept of the data for each force level on the *y* axis is equal to 2 k^-, as indicated in the figure (*arrow*).

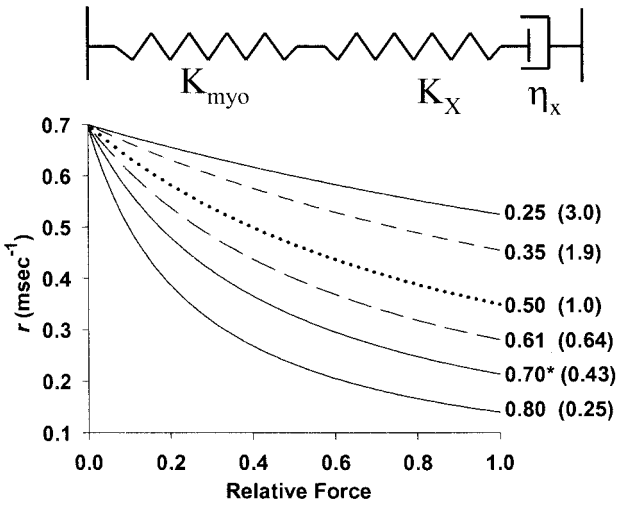

FIGURE 4 (*A*) Schematic illustration of the series components of the model (see Results). (*B*) The force or activation dependence of *r* was generated using Eq. 2 for a range of β values; the values of myofilament compliance as a fraction of C_S at maximum Ca^{2+} activation are given to the right of each curve ($1/K_{myo}/(1/K_{myo} + 1/K^*_X)$), with the corresponding value of β (K_{myo}/K^*_X) in parentheses.

because to do so would require knowledge of the fraction of strong cross-bridges at maximum activation.

Increasing [Ca^{2+}] enhances strong actomyosin interaction, increasing both the relative stiffness of the cross-bridge component (K_X; Figs. 1 and 2) and the apparent viscosity (η_X; Fig. 3). Length changes applied to the ends of the fiber or sarcomere will be partitioned preferentially to the more compliant of the two components. Thus, if K_{myo} is not significantly dependent on the level of activation, increasing force and K_X (decreasing cross-bridge compliance) would result in a smaller fraction of the applied length change being applied to the cross-bridge population, causing an apparent increase in the amplitude of length step required to drop force to zero (Y_0) as the level of activation and force rises (Fig. 2). In addition, the model predicts that with the damped element η_X, a step change in overall length results in a transient change of force following the step that has a time constant $\tau = K/\eta_x$ and a rate $r = 1/\tau$. Because stiffness and compliance are distributed between two components, r is dependent on the ratio K_{myo}/K_X, as follows.

1) If $K_X \ll K_{myo}$, then

$$r' = 1/\tau = K_X/\eta_X$$

2) Assuming that K_X and η_X vary in proportion to normalized force (f), so that $K_X = f K_X^*$ and $\eta_X = f\eta_X^*$(K_X^* and η_X^* are the values at maximum Ca^{2+} activation), then

$$r' = fK_X^*/f\eta_x^*$$

and thus r' would be independent of activation level.

3) On the other hand, if K_{myo} is closer in value to K_X, for the series combination of K_{myo} and K_X:

$$r = (K_{myo} \cdot K_X)/((K_{myo} + K_X)(\eta_x))$$

4) Let β be the proportionality between K_{myo} and K_X^* ($\beta = K_{myo}/K_X^*$), then substitution into the third equation above yields:

$$r' = Z\beta/(\beta + f), \quad (2)$$

where $Z = (K_X^*/\eta_X^*)$.

The model predicts that r should change inversely with the level of isometric force, as found experimentally (Figs. 1–3). To illustrate the behavior of the model, curves describing the activation dependence of k^- were generated using a range of β values are shown in Fig. 4 *B*. For larger β, r has little dependence on force, whereas for smaller values of β, r becomes more strongly force dependent. The ratio Z (K_X^*/η_X^*) is the y-axis intercept at zero force. This simple analysis indicates that any maneuver that causes either a decrease in force or an apparent increase in K_{myo} could decrease Y_0 (increased the stiffness/force ratio; see Fig. 2 *B*) and increase r, without any need to hypothesize an activation dependence of cross-bridge kinetics or cooperative interactions (Martyn and Chase, 1995; Bagni et al., 1988). Furthermore, by determining the force dependence of r and fitting the model to the data we can calculate β and thereby the possible partition of C_S between the myofilament and cross-bridge components in skinned fibers.

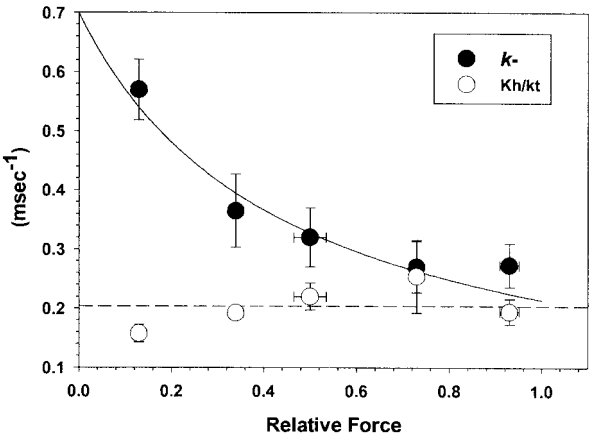

FIGURE 5 The Ca^{2+}-activation dependence of the r-ΔSL (as in Fig. 3) relation was determined over a range of [Ca^{2+}] for seven fibers. For each fiber the values of k^- (●) and Kh/kt (○) at each [Ca^{2+}] were obtained by nonlinear regression analysis of the data with Eq. 1. The pooled data are included in Table 1. The values of k^- in Fig. 5 were fit by Eq. 2 (*solid curve*), and the calculated values of β (0.44) and Z are included in Table 2.

Fitting the model to the activation dependence of *r*

Fig. 5 illustrates that k^- increased with decreasing activation and α was relatively independent of activation level, as previously observed (Martyn and Chase, 1995). As suggested in the Introduction an increase in r (or k^-) could result from the presence of a substantial myofilament compliance. To determine the degree of filament compliance necessary to fit the data in Fig. 5, pooled values of k^- were obtained at different levels of Ca^{2+} activation and fit by Eq. 2. The value of β necessary to fit the data was 0.44 ± 0.12 (mean ± SEM; $n = 7$ fibers) for Ca^{2+}-activated contractions corresponding to a fractional myofilament compliance of 0.69 C_S, a value that is similar to direct measurements of actin filament compliance (Kojima et al., 1994), fiber compliance in rigor (Higuchi et al., 1995), and x-ray diffraction measurements of meridonial myofilament reflections (Wakabayashi et al., 1994; Huxley et al., 1994). The values of k^- obtained at different levels of Ca^{2+} activation are included in Table 1.

Force dependence of k^- when tension is altered by alumino-fluoride or in the absence of Ca^{2+}

The ability of the model to fit the data and yield values of myofilament compliance (Fig. 5; Table 1) that are comparable to that obtained by more direct measurements of myofilament compliance suggests that the activation depen-

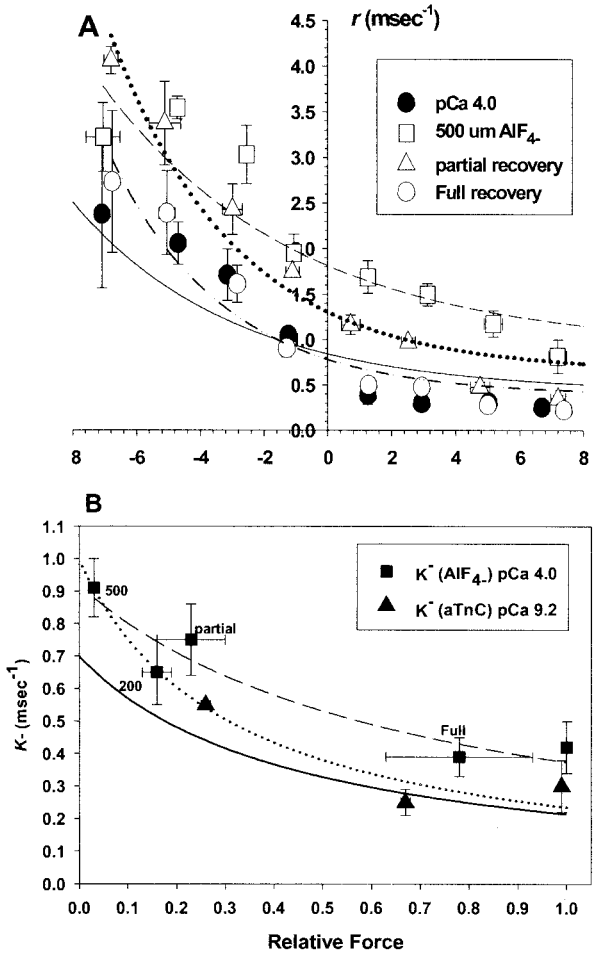

FIGURE 6 (*A*) As described for Figs. 1 and 3, the *r*-ΔSL relation was measured in controls (●, ——) and when force was inhibited with 0.5 mM AlF^{4-} (□; — — —) in pCa 4.0 activating solution (means ± SEM; n = 7 fibers) and allowed to recover from inhibition (○; · · ·). Also, from three fibers of this set data were obtained during partial recovery from force inhibition (△; *dashed*, *double dotted line*). The values of k^- and α for each condition were determined by fitting the data in *A* with Eq. 1. (*B*) The force dependence of k^- derived from the data in *A* is shown (■) along with the curves fits from Eq. 2 (— — —). As described in Results, data from two fibers reconstituted with low and high levels of aTnC in the absence of Ca^{2+} (▲; · · ·) are also included and fit by Eq. 2. The calculated values of β for the data in *B* are included in Table 2. For comparison, the fit curve to the k^- data in Fig. 5 is included (——).

dence of r may result directly from altered cross-bridge binding and force, rather than from effects of Ca^{2+} per se on cross-bridge kinetics. To test this idea in a subset of fibers we inhibited force at pCa 4.0 with alumino-fluoride (AlF^{4-}; 0.5 mM $Al(NO_3)_3$ plus 10 mM F), a phosphate analog that binds to myosin with slow dissociation kinetics (Chase et al., 1994; Smith and Rayment, 1995). As described for Figs. 1 and 3, in Fig. 6 *A* the *r*- ΔSL relation was measured in three fibers when force was inhibited with AlF^{4-} (0.5 mM; □) in pCa 4.0 activating solution and at submaximal force during partial recovery from inhibition when the fibers were activated in pCa 4.0 solution with no AlF^{4-} (△). Finally,

TABLE 2 The relationship of k^- to relative force was fit with Eq. 1 for the conditions described in Table 1

Condition	n	β	Z	% Compliance
Ca	7	0.44 ± 0.12	0.72 ± 0.08	69
AlF^{4-}	*	0.68 ± 0.21	0.92 ± 0.08	60
aTnC	2	0.31 ± 0.34	1.0 ± 0.60	76

The corresponding derived values of β, Z, and the fraction of total fiber compliance from sources other than crossbridges (±SEM) are listed.
*See Legend for Figure 6.

force was allowed to maximally recover in pCa 4.0 with no AlF^{4-} (○). The values of k^- and α for each condition were determined by fitting the data in Fig. 6 *A* with Eq. 1. The dependence of k^- on relative force is shown in Fig. 6 *B* along with the curves fits from Eq. 2. As shown in Fig. 3 at submaximal forces r and k^- are faster, whether force is modulated by changing $[Ca^{2+}]$ (Fig. 5) or by inhibition of force with AlF^{4-} in the presence of maximal $[Ca^{2+}]$ (Fig. 6 *A*). The calculated values of β for the conditions illustrated in Fig. 6 *B* are included in Table 2.

To further test the hypothesis that the apparent activation dependence of r and k^- does not result from altered thin filament Ca^{2+} activation per se, data similar to that in Fig. 6 *A* were obtained when skinned skeletal fibers were activated with a modified cardiac TnC (aTnC) and are included in Fig. 6 *B*. Fibers were reconstituted with a modified form of cTnC (aTnC) in which endogenous cysteine residues 84 and 35 were cross-linked under oxidizing conditions (Hannon et al., 1993; Putkey et al., 1993). aTnC constitutively activated force in the absence of Ca^{2+} (Hannon et al., 1993). The data shown were obtained from two fibers in which force and stiffness were measured when the fibers were fully and partially reconstituted with aTnC at pCa 9.2 (Hannon et al., 1993). As for modulation of force by changing $[Ca^{2+}]$ (Fig. 5) and inhibition with AlF^{4-} (Fig. 6, *A* and *B*), r and k^- increased when force was submaximal. The values of k^-, α, and β obtained with aTnC are included in Tables 1 and 2.

DISCUSSION

The apparent decrease in phase 2 tension redevelopment kinetics (r; Figs. 1, 3, and 5) and increase of Y_0 (Fig. 2 *B*) as the level of Ca^{2+}-activated force increases in skinned psoas fibers from rabbit is similar to that previously reported (Martyn and Chase, 1995). We originally interpreted those results as being consistent with either a Ca^{2+} dependence of kinetic steps in the cross-bridge cycle related to phase 2 or a cooperative mechanism by which the probability of transition from attached but low-force states into strongly bound force-producing states increased as force increased (Bagni et al., 1988). Both these interpretations assume that the contribution of structures other than cross-bridges to sarcomere compliance was no more than 10–20%

of C_S (Ford et al., 1986). However, direct measurements of isolated thin filament compliance (Kojima et al., 1994; Isambert et al., 1995), low-angle x-ray diffraction of fibers (Huxley et al., 1994; Wakabayashi et al., 1994), and the length dependence of C_S in the rigor state (Higuchi et al., 1995) all suggest that ~50% of the C_S resides in the thin and thick filaments and other non-cross-bridge structures. Thus, it was necessary to determine whether the presence of a significant non-cross-bridge compliance could influence measurements of Y_0 and phase 2 tension transients and the interpretations of the data. Our approach has been to develop a simple model (Results; Fig. 4) in which C_S is partitioned between two elastic elements, K_{myo}, which consists of contributions from thick and thin filaments, as well as other sarcomeric structures (z-bands, titin, etc.), and K_X, the elasticity of strongly bound actomyosin cross-bridges in the overlap zone between thin and thick filaments. By assuming that the level of Ca^{2+} activation had no direct effect on r and the apparent activation dependence of r (Figs. 1 *A*, 3, and 5) occurred only because $K_{myo} \approx K_X$ during maximum activation, fitting Eq. 2 to the data (Figs. 4 and 5) yielded values of β (K_{myo}/K_X^*) and myofilament compliance (0.60–0.76 C_S; Table 2) that were consistent with measurements of myofilament stiffness made by mechanical measurements on isolated thin filaments and fibers in rigor and structural measurements on whole muscle. Furthermore, similar values of β were obtained by measuring the activation dependence of Y_0 (Fig. 2 *B*; Table 1). These similarities suggest that the apparent activation or force dependence of Y_0 and r could result primarily from the presence of a significant myofilament compliance and not from Ca^{2+} or activation dependence of cross-bridge transitions between cross-bridge states.

Comparison of sarcomere compliance measurements in intact and skinned fibers

There is some conflict regarding the magnitude of non-cross-bridge compliance when measured mechanically in skeletal fibers. For example, compliance measurements made in intact frog fibers (Bagni et al., 1990; Ford et al., 1986; Linari et al., 1998) and glycerinated rabbit psoas fibers in rigor (Tawada and Kimura, 1984) indicate that only ~10–20% C_S results from non-cross-bridge structures, whereas the results of Higuchi et al. (1995) suggest a value of 50% C_S. This conflict could result from differences between the various experimental approaches. In the experiments of Higuchi et al. (1995), SL was varied over a range where overlap between thin and thick filaments was constant for fibers in rigor; the compliance of that region was assumed to be invariant. In the study by Tawada and Kimura (1984) the degree of myofilament overlap and the compliance of the overlap region varied. A feature common to both procedures is that the length of the non-overlap region increased with increased SL. Analysis of the data from Higuchi et al. (1995) lead to the conclusion that a very significant component of total compliance resided in the thin filaments, whereas the results of Tawada and Kimura (1984) are not consistent with a large non-cross-bridge component of compliance. In fact, the amount of non-cross-bridge compliance of skinned rabbit fibers in rigor, as determined at SL above 2.5 μm (Tawada and Kimura, 1984), was the same as that described for intact electrically stimulated frog fibers (Bagni et al., 1990; Ford et al., 1986).

For fibers in rigor it was assumed that the compliance of the overlap region was constant and low, and only the compliance of the non-overlap region changed when SL is altered (Higuchi et al., 1995). In contrast, during active contractions the compliance of the overlap region would depend on the level of activation (Higuchi et al., 1995) and the number of interacting actomyosin cross-bridges (Gordon et al., 1966, 2000). It is noteworthy that the dependence of compliance on the level of isometric force in our activated fibers is similar in form to that observed in rigor (Higuchi et al., 1995). In both studies, compliance is highest at low force and decreases to a plateau at high forces. In our case, a portion of the high C_S at low forces is presumably due to the lower level of thin filament activation and actomyosin interaction (Fig. 2 *A*), whereas for fibers in rigor, the higher compliance at low degrees of cross-bridge strain must be attributed to the nonlinear properties of the non-overlap thin filament stress/strain relationship.

Possible contribution of an activation-dependent K_{myo}

The model (Fig. 4) assumes that only the value of K_X depends on the level of thin filament activation. However, the flexural rigidity and stiffness of isolated thin filaments not only depends on the presence of regulatory complexes but is also altered by Ca^{2+} binding to TnC (Isambert et al., 1995; Kojima et al., 1994). The flexural rigidity of thin filaments, and presumably their axial stiffness, was found to be maximal in actin filaments reconstituted with tropomyosin and troponin, whereas the rigidity of these regulated filaments decreased by a factor of 2 when Ca^{2+} was bound to TnC, to that found for unregulated actin filaments (Isambert et al., 1995). Furthermore, the compliance of thin filaments determined by flexural rigidity was similar to that obtained by direct mechanical measurements of isolated actin filament compliance (Kojima et al., 1994). Thus, one could speculate that at lower levels of activation, thin filament compliance would decrease. At a given SL, this would result in a greater proportion of an applied length change being partitioned to the attached cross-bridges; i.e., Y_0 would decrease and the stiffness/force ratio increase at low activation, as observed (Fig. 2 *B*; Table 1).

If structural changes of the thin filament alter compliance, then cross-bridge binding could contribute to these changes as well. For example, thin filament activation is dependent

on and enhanced by strong cross-bridge binding in solution studies (McKillop and Geeves, 1993; Geeves and Lehrer, 1994). Thus, cycling cross-bridges could alter thin filament compliance in the overlap zone in a way analogous to Ca^{2+} binding (Isambert et al., 1995). Furthermore, this effect could extend into the non-overlap zone a fixed distance from the A-I band boundary; at shorter lengths this fixed distance would be a greater proportion of the I band. The recent observation that cross-bridge binding in the overlap zone between thick and thin filaments enhances binding of myosin S1 subfragments for a distance into the non-overlap I band (Swartz et al., 1996) supports this idea. Because cross-bridge binding is maximal in rigor, this effect could increase the apparent myofilament compliance of fibers in rigor (Higuchi et al., 1995). On the other hand, the relative fraction of strong, cycling cross-bridge binding during activation is a matter of controversy with estimates ranging from 10–15% (Allen et al., 1996; Howard, 1997; Daniel et al., 1998; Corrie et al., 1999) to 80% (Ford et al., 1986; Bagni et al., 1990). If the lower estimates of cycling cross-bridge binding are correct, it is unlikely that this small fraction could influence filament compliance by directly altering thin filament structure, whereas the opposite may be true if the higher estimates are found to be accurate.

Although Ca^{2+} binding and cross-bridge-induced changes in thin filament structure could increase thin filament compliance (β (K_{myo}/K_X^*) would vary with the level of contractile activation), our data indicate that this may not be the case. For example, the force dependence of Y_0 (Table 1) and r (Figs. 1, 3, and 5) are similar whether force is changed by varying [Ca^{2+}] or by inhibition with AlF^{4-} (Fig. 6, *A* and *B*; Table 2) in the presence of maximal [Ca^{2+}] (pCa 4.0). Although the data do not exclude an activation dependence of thin filament compliance, the finding that Y_0 and r are similar at low force levels (Table 1), whether achieved with low [Ca^{2+}] or high [Ca^{2+}] with AlF^{4-}, suggests that the contribution of activation- or [Ca^{2+}]-dependent changes in thin filament compliance to C_S is small.

Consequences to measurements and interpretation of cross-bridge kinetics

If, as we propose, myofilament compliance has a significant influence of the apparent rate of phase 2 tension recovery (r) then this should be extended to all measurements of cross-bridge kinetics, including k_{TR} (see Luo et al., 1994) and sinusoidal measurements of fiber stiffness (Kawai et al., 1981) obtained under conditions in which the degree of cross-bridge binding is altered. For example, inspection of Eq. 2 indicates that at any force level, transient rates will be underestimated by the factor $\beta/(f + \beta)$. At low levels of activation force ($f \ll 1$) kinetics would be little affected by filament compliance ($K_{myo} \gg K_X$), whereas at maximum force ($f = 1$) the rate would be underestimated by the factor $\beta/(1 + \beta)$. Therefore, at maximum force, k^- in Fig. 5 is underestimated by ~70% ((1 − 0.43/1.43) × 100)). Furthermore, Eq. 2 also indicates that the underestimation of rate does not depend on the absolute value of the rate of transient tension change being measured. Thus, if correction for a distribution of C_S between cross-bridges and myofilaments is not made, the rates of tension transients may be underestimated by the factor $\beta/(f + \beta)$, with the distortion increasing as maximum force is approached.

SUMMARY

In actively contracting skinned rabbit skeletal fibers we found that C_S, Y_0, and the rate of phase 2 tension redevelopment (r) were all dependent on the level of Ca^{2+} activation. C_S and r decreased, whereas Y_0 increased, as the level of contractile activation and force increased. The results were similar when force was altered by varying [Ca^{2+}], inhibition with AlF^{4-} at high [Ca^{2+}], or without Ca^{2+} by reconstitution of thin filaments with aTnC. Fitting these results with a simple three-component series model of sarcomeric compliance resulted in an estimation of the fraction of total compliance due to myofilaments that was comparable to more direct measurements of filament compliance in isolated thin filaments and in activated intact muscles. Thus, the previous descriptions of activation-dependent cross-bridge kinetics and Y_0 could be explained in large part by the presence of a substantial non-cross-bridge component of C_S.

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